1.5 The Maximum Likelihood Estimator and the Information Matrix

We have now talked about how to construct likelihoods in a variety of settings, now we can use those constructions to formalize how we make inferences about model parameters.

J paraveter estimation, hypotrosis tests, Confidence intervals. We often restrict affection to Likenhoods that are continuously diffrentiable wit \mathcal{G} . In this Recall the score function

$$S(\underline{\theta}) = S(\underline{P}), \theta) = \begin{pmatrix} \frac{\partial l(\underline{\theta})}{\partial \theta_{1}} \\ \vdots \\ \vdots \\ rondom because it \\ depends on the dota Y. \end{pmatrix} = \begin{pmatrix} \frac{\partial l(\underline{\theta})}{\partial \theta_{1}} \\ \vdots \\ \vdots \\ \vdots \\ \frac{\partial log L(\underline{\theta}|Y)}{\partial \theta_{b}} \end{pmatrix}$$

Generally, the maximum likelihood estimator $\hat{\boldsymbol{\theta}}_{\text{MLE}}$ is the value of $\boldsymbol{\theta}$ where the maximum (over the parameter space Θ) of $L(\boldsymbol{\theta}|\boldsymbol{Y})$ is attained.

$$\hat{\underline{\theta}}_{\text{MLE}} = \arg_{\text{MOX}} L(\underline{\theta}|\underline{Y}) \iff L(\underline{\hat{\theta}}_{\text{MLE}}|\underline{Y}) \ge L(\underline{\theta}|\underline{Y}) \quad \forall \underline{\theta} \in HOH$$

Under the assumption that the log-likelihood is continuously differentiable, then

$$S(\hat{\theta}_{ME}) = 0.$$

But not always (?!).

Example (Exponential threshold model): Suppose that Y_1, \ldots, Y_n are iid from the exponential distribution with a threshold parameter μ ,

$$f(y;\mu) = egin{cases} \exp\{-(y-\mu)\} & \mu \bigotimes y < \infty \ 0 & ext{otherwise}, \end{cases}$$

for $\infty < \mu < \infty$.

$$L(\mu|Y) = \prod_{i=1}^{n} f(Y_{i};\mu) = \prod_{i=1}^{n} \exp\left(-(Y_{i}-\mu)\right) \operatorname{I\!I}\left(\mu < Y_{i}\right).$$

$$= \exp\left(-n\overline{Y}\right) \exp\left(n\mu\right) \prod_{i=1}^{n} \operatorname{I\!I}\left(\mu < Y_{i}\right).$$

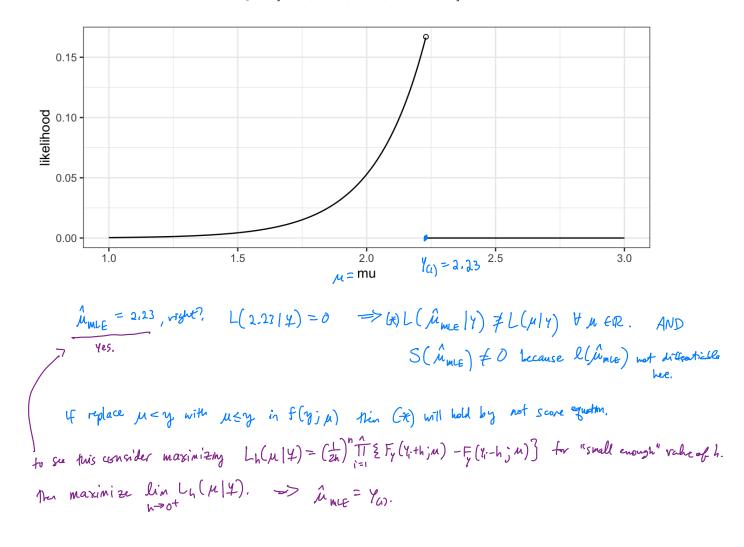
$$= \exp\left(-n\overline{Y}\right) \exp\left(n\mu\right) \prod_{i=1}^{n} \operatorname{I\!I}\left(\mu < Y_{i}\right).$$

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Consider the artificial data set y = [2.47, 2.35, 2.23, 3.53, 2.36].



Rest of this section: assume support doesn't depend on the periorder value. **1.5.1 The Fisher Information Matrix** Yi $\stackrel{\text{dimension of } \mathcal{D}}{\text{The Fisher information matrix } I(\theta)}$ is defined as the $b \times b$ matrix where $I_{ij}(\theta) = E\left[\{\frac{2}{2}\partial_{\theta_i} \log f(Y_{ij}, \theta)\}\{\frac{2}{2}\partial_{\theta_j} \log f(Y_{ij}, \theta)\}\right]^{-1}$ (s this random? No(, it's on expectation! Notice: this is the "information" is one observation. (note Y_i).

In matrix form,

$$I(\theta) = E \left[\left(\frac{\partial}{\partial \theta^{+}} \log f(Y_{i}; \theta) \right) \left(\frac{\partial}{\partial \theta} \log f(Y_{i}; \theta) \right) \right]$$

$$row rector$$

$$rector.$$

$$II$$
Let $S(Y_{i}; \theta) = \begin{cases} \frac{\partial}{\partial \theta} \log f(Y_{i}; \theta) \end{cases}^{T} \leftarrow column rector.$

$$C \text{ score contribution.}$$
Then $I(\theta) = E \left[S(Y_{i}; \theta) S(Y_{i}; \theta)^{T} \right].$

$$f$$

$$A \text{ gain this depends on 1 descration (not in of them).}$$

Fisher information facts:

- 1. The Fisher information matrix is the variance of the score contribution.
 - Why? $E[S(Y_{i}, \Phi)] = 0$ Fact (1) from GLM section.

Bigust 2) If regularity conditions are met,

$$\sqrt{n}(\hat{\theta}_{MLE} - \theta) \xrightarrow{d} N_b(0, I(\theta)^{-1}).$$

$$\frac{\sqrt{n}(\hat{\theta}_{MLE} - \theta)}{\frac{d}{2}} \xrightarrow{d} N_b(0, I(\theta)^{-1}).$$

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$$\frac{\sqrt{n}(\theta_{MLE} - \theta)}{\frac{d}{2}} \xrightarrow{d} N(\theta, I(\theta)^{-1}).$$

We will prove this result for 6=1. (later).

- 3. If b = 1, then any unbiased estimator must have variance greater than or equal to $\{nI(\theta)\}^{-1}$
 - Cramer-Rao lower bound. If $b \ge 1$: If Σ is the asymptotic courted vix of any other consistent estimator, then $Z = I(\theta)^{-1}$ is possitive definite.
- 4. The information matrix is related to the curvature of the log-likelihood contribution.

$$\begin{split} \mathbf{I}(\underline{\theta}) &= \mathbf{E}\left[\left(\frac{\partial}{\partial \underline{\theta}^{T}} \log f(Y_{i};\underline{\theta})\right)\left(\frac{\partial}{\partial \underline{\theta}} \log f(Y_{i};\underline{\theta})\right)\right] \\ &= \mathbf{E}\left[-\frac{\partial^{2}}{\partial \underline{\theta}} \partial \underline{\theta}^{T} \log f(Y_{i};\underline{\theta})\right] \qquad \text{assuming L is twize differentiable and $using fact Θ from GLM such im.$} \\ &= \mathbf{E}\left[-\frac{\partial}{\partial \underline{\theta}} \partial \underline{\theta}^{T} \log f(Y_{i};\underline{\theta})\right] \qquad using fact Θ from GLM such im.$} \\ &= \mathbf{E}\left[-\frac{\partial}{\partial \underline{\theta}} S(Y_{i};\underline{\theta})\right] \qquad \text{(unity another uay).} \end{split}$$

1.5.2 Observed Information

The information matrix is not random, but it is also not observable from the data. You need knowledge of the distribution to calculate in

Would be great the use
$$I(\hat{\theta}_{MLE}) = E \left\{ -\frac{2^2}{\partial \theta \partial \theta} \log f(Y_i; \underline{\theta}) \right|_{\underline{\theta}} = \hat{\theta}_{MLE}$$

Let Y_1, \ldots, Y_n be iid with density $f_Y(y_i; \boldsymbol{\theta})$. The log likelihood is defined as

taking two derivatives and dividing by n results in

define
$$\overline{I}(Y, \underline{\theta}) = \frac{4}{n} \sum_{i=1}^{n} \overline{\xi} - \frac{2^2}{2\underline{\theta}} \log f_{y}(Y_{i}; \underline{\theta})$$

1 average curvature contribution.

$$(f \quad I(\underline{\theta}) = E \underbrace{\xi}_{-\frac{\partial^2}{\partial \underline{\theta} \partial \underline{\theta}^*}} \log f(\underline{Y}_i; \underline{\theta}) \underbrace{\xi}_{-\frac{\partial^2}{\partial \underline{\theta} \partial \underline{\theta}^*}} \log f(\underline{Y}_i; \underline{\theta}) \underbrace{\xi}_{-\frac{\partial^2}{\partial \underline{\theta}^*}} \log f(\underline{\theta}_i; \underline{\theta}) \underbrace{\xi}_{-\frac{\partial^2}{\partial \underline{\theta}^*}} \log f(\underline{\theta}) \underbrace{\xi}_{-\frac{\partial$$

$$\Rightarrow$$
 $I(Y, \hat{\theta}_{MLE})$ scens like a natural astimator for $I(\theta)$.

Definition: The matrix $n\bar{I}(Y; \hat{\theta}_{MLE})$ is called the sample information matrix, or the observed information matrix.

Note: I(b) is the expected curvature of the log-likelihood surface from one observation The observation = r... 1 pe observed information nI(x; ônce) is from a sample of size n and does depend on sample size. Recall $\hat{\theta}_{MLE} \sim N(\theta, \xi \wedge I(\theta) \zeta')$ (*) To get approximate variance of Brug for sample of size n, we need the matrix to depend on n.

Why use $I(\boldsymbol{\theta}) = \mathbb{E}\left[-\frac{\partial^2}{\partial \boldsymbol{\theta} \partial \boldsymbol{\theta}^{\top}} \log f(Y_1; \boldsymbol{\theta})\right]$ as the basis for an estimator, rather than $I(oldsymbol{ heta}) = \mathrm{E}\left[\left\{rac{\partial}{\partial oldsymbol{ heta}^ op} \mathrm{log}\, f(Y_1;oldsymbol{ heta})
ight\}\left\{rac{\partial}{\partial oldsymbol{ heta}} \mathrm{log}\, f(Y_1;oldsymbol{ heta})
ight\}
ight]?$

The Messian (curvature) @ Ômite is readily available from optimization methods => n I (x, ôme,) can be computed easily.

A Hernatively could use
$$\overline{I}^{*}(Y, \underline{e}) = \frac{1}{n} \sum_{i=1}^{n} \left[\frac{\partial}{\partial \underline{e}^{+}} \log f(\underline{Y}_{i}, \underline{e}) \right]^{2} \left\{ \frac{\partial}{\partial \underline{e}^{-}} \log f(\underline{Y}_{i}; \underline{e}) \right\}^{2}$$

$$\left(\text{License} E[\overline{I}^{*}(Y, \underline{e})] = I(\underline{e}) \text{ also} \right),$$

This is not typically used unless specification of f i'lless clear (moul misspecification), $(\overline{I}(4, \pm))$ is more efficiant)

we will see this again later.

Now let's prove the asymptotic normality of the MLE (in the scalar case).

$$\begin{aligned} \text{MScFul } 4\text{red}S: \text{ for } X_{1,-}, \forall x_{n} \text{ if } V \text{ we } Y_{1} \in e^{X_{1}} \otimes e^{X_{1}} \otimes e^{X_{1}} \in e^{X_{1}}, \\ \text{ULL } : \quad \overline{X}_{n} = \frac{1}{n} \frac{1}{2} \sum_{i=1}^{n} | \rightarrow i^{2} \text{E}[\Sigma_{i}], \\ \text{CLT } : \quad \overline{C}\left[\overline{X}_{n} = -EX_{1}\right] = \overline{\mu} \left[\frac{1}{n} \sum_{i=1}^{n} X_{i} = EX_{1}\right] \xrightarrow{d} N(0, e^{X_{1}}), \\ \text{Lt } Y_{i} \stackrel{\text{ifd}}{}^{d}S_{y}(\gamma_{i};\theta) \text{ and } \hat{\theta}_{\text{made}} \text{ is such } \theta + \frac{1}{4\pi} f(\mu)|_{0} \stackrel{\text{o}}{=} 0, \\ & \text{S}(\hat{\theta}_{\text{made}}). \end{aligned} \\ \text{Lt } S(\theta) = \frac{1}{4\pi} f(\theta) = \frac{2}{1} \sum_{i=1}^{n} \frac{1}{4\theta} \left[h_{g} f(Y_{i};\theta) \\ & = \sum_{i=1}^{n} S(Y_{i},\theta) \text{ where } e(Y_{i},\theta) = \frac{1}{4\theta} \left[h_{g} f(Y_{i};\theta) \\ & = \sum_{i=1}^{n} S(Y_{i},\theta) \text{ where } e(Y_{i},\theta) = \frac{1}{4\theta} \left[h_{g} f(Y_{i};\theta) \\ & = \sum_{i=1}^{n} S(Y_{i},\theta) \text{ where } e(Y_{i},\theta) = \frac{1}{4\theta} \left[h_{g} f(Y_{i};\theta) \\ & = \sum_{i=1}^{n} (1, S(\theta)) = 0 \text{ ord } Vor\left[S(Y_{i},\theta) \right] = T(\theta) \text{ ord } \sum_{i=1}^{n} S(Y_{i},\theta) \right]_{i=1}^{n} \text{ are } i : d : e^{X_{1}}, \\ & \Rightarrow r_{n} \left(\frac{1}{n} S(\theta) - \theta \right) \xrightarrow{d} N(0, T(\theta)) \text{ by } CLT \\ & \Leftrightarrow (nL(\theta))^{X_{n}} S(\theta) \xrightarrow{d} Z_{n} \sum_{i=1}^{n} \frac{1}{4\theta} \frac{1}{2\theta} \frac{1}{\theta} \frac{1}{\theta} \frac{1}{\theta} S(Y_{i},\theta), \text{ Then } E\left[-\frac{1}{d\theta} S(Y_{i},\theta) \right] = T(\theta), \\ & \text{Sceadly}, \quad \text{B.t } J(\theta) = - \sum_{i=1}^{n} \frac{1}{4\theta} \frac{1}{2\theta} \frac{1}{\theta} \frac{1}{\theta} \left(\hat{\theta}_{\text{ME}} - \theta \right) \Rightarrow \hat{\theta}_{\text{ME}} \otimes e^{X_{1}} X_{1} \text{ are } F_{n} \text{ allow } \text{ for Taylor Exposition.} \\ & 0 = S\left(\hat{\theta}_{\text{me}} \right) \approx S\left(\theta \right) + \frac{dS(\theta)}{d\theta} \left(\hat{\theta}_{\text{me}} - \theta \right) \Rightarrow \hat{\theta}_{\text{made}} = \theta \times - \frac{1}{4\theta} S(\theta), \\ & 0 = S\left(\hat{\theta}_{\text{me}} \right) \approx S\left(\theta \right) + \frac{dS(\theta)}{d\theta} \left(\hat{\theta}_{\text{me}} - \theta \right) \Rightarrow \hat{\theta}_{\text{mad}} \otimes \theta \times - \frac{1}{4\theta} \sum_{i=1}^{n} S(\theta), \\ & 0 = S\left(\hat{\theta}_{\text{mad}} \right) \approx S\left(\theta \right) + \frac{dS(\theta)}{d\theta} \left(\hat{\theta}_{\text{me}} - \theta \right) \Rightarrow \hat{\theta}_{\text{mad}} \otimes \theta \times - \frac{1}{4\theta} \sum_{i=1}^{n} S(\theta), \\ & T(\theta) = \pi^{T(\theta)}, \\ & T(\theta)$$

Note the argument to replace $I(\theta)$ by $\overline{I}(\hat{\theta}_{MLE})$ in the asymptotic result is justified by convergence in probability. The argument is generalized to $\underline{\theta}$ by interpreting the scace as a bxt vector, $\overline{I}(\underline{\theta})$ as a bxb matrix, $\underline{Z} \sim N_b(\underline{O}, \underline{L}_b)$.

6=1.