Let's try it.

```
library(evd)
# simulate data with alpha = 0.5
alpha <- 0.5
z <- rmvevd(500, dep = alpha, d = 5, mar = c(1, 1, 1))
## bivariate density
d_bivar <- function(z, alpha){
    #here "z" is a single observation (ordered pair)
    inside <- z[1]^(-1/alpha) + z[2]^(-1/alpha)
    one <- exp(-inside^alpha)
    two <- (z[1]*z[2])^(-1 / alpha - 1)
    three <- (1 / alpha - 1)*inside^(alpha - 2)
    four <- inside^(2 * alpha - 2)
    one*two*(three + four)
}
d bivar(c(4, 5), alpha = alpha)</pre>
```

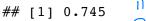
[1] 0.003650963

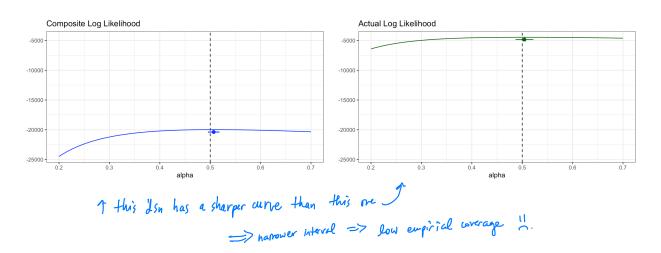
dmvevd(c(4,5), dep = alpha, d = 2, mar = c(1,1,1))

[1] 0.003650963

```
## estimate alpha
log_pair_lhood <- function(alpha, z) {
    #here "z" is bivariate matrix of observations
    inside <- z[, 1]^(-1 / alpha) + z[, 2]^(-1 / alpha)
    log_one <- -inside^alpha
    log_two <- (-1 / alpha - 1) * (log(z[, 1]) + log(z[,
2]))
    three <- (1 / alpha - 1) * inside^(alpha - 2)
    four <- inside^(2 * alpha - 2)
    contrib <- log_one + log_two + log(three + four)
    return(sum(contrib))
  }
```







So, it looks like the point estimate from the pairwise likelihood is ok, but we need to be able to get an appropriate measure of uncertainty.

CI:
Recall if
$$\hat{\theta}_{\text{MLE}}$$
 is the estimate from the const model and $\underline{\theta}$ is the three value of the parameter, then
 $\int n\left(\underline{\theta}_{\text{MLE}} - \underline{\theta}\right) - \frac{1}{d} N(0, T(\underline{\theta})^{-1})$
So for fixed, large n , $\hat{\theta}_{\text{MLE}} \sim N(\underline{\theta}, \frac{1}{n} T(\underline{\theta})^{-1})$
where $T(\underline{\theta}) = E\left[\left(\frac{9}{2\theta^2} \log f(Y_{1,0}\underline{\theta})\right)\left(\frac{\theta}{\partial \underline{\theta}} \log f(Y_{1,0}\underline{t})\right)\right]$ "variance of the score"
If this is
 $the corrections = E\left[-\frac{\partial^2}{\partial \underline{\theta} \partial \underline{\theta}^2} \log f(Y_{1,0}\underline{\theta})\right]$ "hession of score contribution"

$$\frac{1}{n} \overline{\Gamma(\theta)} = [n \overline{\Gamma(\theta)}] + n\overline{\Gamma(\theta)} \text{ is approximated with } n \overline{T(\theta)} = -\frac{\partial^2 l(\theta)}{\partial \theta^T}$$
This is wrong in the misspecified case!

The proper adjustment is (A.C. Davidson, statistical models, p. 147).

$$\begin{array}{c} \hat{\theta}_{EE} \sim N(\Phi, I(\theta) I(\theta)') & \text{where} \quad K(\theta) = n E\left[\left(\frac{2}{3\theta^{T}} \log f_{p}(y_{1}; e)\right)\left(\frac{2}{\theta^{0}} \log f_{p}(y_{1}; e)\right)\right] \\ \hat{\theta}_{EE} \sim N(\Phi, I(\theta) I(\theta)') & \text{where} \quad K(\theta) = -n E\left[\frac{2^{2}}{3\theta^{3}\theta^{T}} \log f_{p}(y_{1}; e)\right] \\ \hat{\eta}_{estimation} & \text{sandwich estimator''} & \text{where} \quad f_{p} \text{ is the } \underline{pairwise} \text{ density}. \\ \hat{\eta}_{the} & \text{incorrectly specified wolde.} \end{array}$$

We will approach this form a more general discussion of M-estimator/estimating equations. (not just pairwise).

1 Introduction

There are 2 parts of a fully specified statistical model: () Systematic part (mean) used for answering the underlying scientific question \longrightarrow => likelihood (a) distributional assumptions about the random part of the model inference. We want to develop robust inference so that misspecification of (a) doesn't invalidate the inference. => like want to develop robust inference so that misspecification of (b) doesn't invalidate the inference. => like want to develop robust inference so that misspecification of some equations. => like want to define an estimator of inference as the solution to some equation, but it might not (me from the derivative of a log likelihood.

M-estimators are solutions of the vector equation

$$\sum_{i=1}^{n} \psi(Y_{i}, \theta) = \mathbf{0}, \text{ i.e. if } \stackrel{o}{\not=} \text{ is en } \text{"M-estimator",}$$
$$\stackrel{\circ}{z} \Psi(Y_{i}, \hat{\theta}) = \mathbf{0}.$$

Notes:
Yi are independent (not necessarily i.d. e.g. regression),

$$\underline{P}$$
 is a b-din, parameter
 \underline{Y} is a known b×1 function that does not depend on \overline{i} or n , but can depend on \underline{Z}_i for regression.
regression: above equation $\frac{\overline{Z}}{\overline{i}} \underline{Y}(\underline{Y}_i, \underline{Z}_i, \underline{P}) = \underline{0}$.
In the likelihood setting, what is $\underline{\psi}$?

Y is the derivative of the log-likelihood (the score function).

There are 2 types of M-estimators.
()
$$p$$
-type: solutions $\underline{\theta}$ which minimize $\widehat{\underline{\xi}}_{i=1}^{2} P(\underline{Y}_{i}, \underline{\theta})$
(a) Ψ -type: solutions $\underline{\theta}$ to $\widehat{\underline{\xi}}_{i=1}^{2} \Psi(\underline{Y}_{i}, \underline{\theta}) = \underline{0}$.
Of ten an M-estimator is of both types, i.e. if p has a continuous first derivative out $\underline{\theta}$, then

on M-estimator of $\Psi^{-1}y_{pe}$ is on M-estimate of $p^{-1}y_{pe}$ with $\Psi(y, \underline{e}) = \nabla_{\theta} p(y_{1} \underline{e})$.

1 Introduction

Example: Let Y_1, \ldots, Y_n be independent, univariate random variables. Is $\theta = \overline{Y} = \frac{1}{n} \sum_{i=1}^{n} Y_i$ an M-estimator?

1) Y -type? $\theta = \frac{1}{2} \frac{z}{Y_i}$ $\Rightarrow 0 = \frac{1}{n} \stackrel{\circ}{\varepsilon} Y_{i} - \theta = \stackrel{\circ}{\varepsilon} \frac{1}{n} (Y_{i} - \theta) = \stackrel{\circ}{\varepsilon} (Y_{i} - \theta) \Rightarrow \Psi(Y_{i}, \theta) = Y_{i} - \theta$ (2) p-type? What does the sample mean minimize? $M = \sum_{i=1}^{n} (Y_{i} - \theta)^{2} = \sum_{i=1}^{n} \rho(Y_{i}, \theta)$ $= \frac{2}{2} \frac{y_i^2}{y_i^2} - 2\theta \frac{2}{2} \frac{y_i}{y_i} + h\theta^2$ To minimize, $\frac{\partial M}{\partial 4} = -2 \sum_{i=1}^{n} Y_i + 2n\theta = 0$ $\theta = \frac{1}{n} \frac{\hat{z}}{\hat{z}_i} Y_i$ M-2(4: 0) ۶0 Ÿ

> We will mainly focus on Y-type M-estimators because it is more straight forward to get our Scadwich estimator matrix.

But can be useful to think of underlying p-type estimator you had to take derivative to get 4-type.

8

MAD

Example: Consider the mean deviation from the sample mean, A measure of spread.

$$\hat{ heta}_1 = rac{1}{n}\sum_{i=1}^n |Y_i - \overline{Y}|.$$

Is this an M-estimator?

To calculate this $\hat{\theta}_{1}$ requires 2 steps: (i) Calculate \overline{Y} \implies no single equation of the term $\sum_{i=1}^{n} \Psi(Y_{i}, \theta) = 0$ can be found. (ii) Calculate MAD But a system of equations of Ψ -type can be written! Ut $\theta_{2} = \overline{Y}$ $\Psi_{2}(Y_{1}, \theta_{2}) = Y - \theta_{2}$ $\Psi_{1}(Y_{1}, \theta_{1}, \theta_{2}) = |Y_{1} - \theta_{1}$ So $\hat{\theta} = (\hat{\theta}_{1}, \hat{\theta}_{2})$ with solve $\sum_{i=1}^{n} \Psi(Y_{1}, \hat{\theta}_{1}, \hat{\theta}_{2}) = (\sum_{i=1}^{n} (Y_{1} - \hat{\theta}_{2} | - \hat{\theta}_{1}))$ $\sum_{i=1}^{n} \Psi(Y_{1}, \hat{\theta}_{1}, \hat{\theta}_{2}) = (\sum_{i=1}^{n} (Y_{1} - \hat{\theta}_{2} | - \hat{\theta}_{1}))$ $\sum_{i=1}^{n} \Psi(Y_{1}, \hat{\theta}_{1}, \hat{\theta}_{2}) = (\sum_{i=1}^{n} (Y_{1} - \hat{\theta}_{2} | - \hat{\theta}_{1}))$

Even though at first the MAD doesn't look like an m-estimator, with a little work we can write it as one.

2 Basic Approach (the theory).

M-estimators are solutions of the vector equation

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$$\sum_{i=1}^{n} \psi(\boldsymbol{Y}_{i}, \boldsymbol{ heta}) = \boldsymbol{0}.$$
 Not case.

but what are they estimating? Some true parameter \mathcal{Q}_o , where

$$(\mathcal{H}) \ \mathsf{E}_{\mathsf{F}}\left[\Psi(\mathsf{Y}_{\mathsf{I}}, \underline{\mathsf{P}}_{\mathsf{0}})\right] = \int \Psi(\mathsf{Y}_{\mathsf{I}}; \underline{\mathsf{P}}_{\mathsf{0}}) \, \mathsf{d}\mathsf{F}(\mathsf{Y}) = \mathcal{O} \ \mathsf{where} \ \mathsf{Y}_{\mathsf{I}} \sim \mathsf{F}$$

Example (Sample Mean, cont'd): Recall we said $\theta = \overline{Y} = \frac{1}{n} \sum_{i=1}^{n} Y_i$ is an M-estimator for $\psi(Y_i, \theta) = Y_i - \theta$. What is the true parameter?

The true parameter solves
$$S(y - \theta_0) dF(y) = 0$$

 $\implies Sy dF(y) = \theta_0$
This agrees we be definition of the population mean.

Recall pe 5-dimensional motivating example. We said the & which maximizes the pairwise likelihood seems like it would be a good estimator for do. We didn't show this. To do so, we would read to use (*). Try this at home.