

Estimating Equations

Example: Consider the $\mathbf{Z} = (Z_1, \dots, Z_5)^\top$ with cdf

$$F(\mathbf{z}; \alpha) = \exp\left\{-\left(z_1^{-\frac{1}{\alpha}} + z_2^{-\frac{1}{\alpha}} + z_3^{-\frac{1}{\alpha}} + z_4^{-\frac{1}{\alpha}} + z_5^{-\frac{1}{\alpha}}\right)^\alpha\right\}, \quad \mathbf{z} \geq \mathbf{0}, \alpha \in (0, 1].$$

Comments:

1. F is max-stable.

2. Z_1, \dots, Z_5 are exchangeable.

Let's consider the likelihood.

How about if we were to just use pairs of points to estimate α ?

If we just used $(z_{1i}, z_{2i}), i = 1, \dots, n$ would the likelihood based on the bivariate density be a good estimator for α ?

Let's try it.

```
library(evd)
# simulate data with alpha = 0.5
alpha <- 0.5
z <- rmvevd(500, dep = alpha, d = 5, mar = c(1, 1, 1))

## bivariate density
d_bivar <- function(z, alpha){
  #here "z" is a single observation (ordered pair)
  inside <- z[1]^(-1/alpha) + z[2]^(-1/alpha)
  one <- exp(-inside^alpha)
  two <- (z[1]*z[2])^(-1 / alpha - 1)
  three <- (1 / alpha - 1)*inside^(alpha - 2)
  four <- inside^(2 * alpha - 2)
  one*two*(three + four)
}

d_bivar(c(4, 5), alpha = alpha)
```

```
## [1] 0.003650963
```

```
dmvevd(c(4,5), dep = alpha, d = 2, mar = c(1,1,1))
```

```
## [1] 0.003650963
```

```
## estimate alpha
log_pair_lhood <- function(alpha, z) {
  #here "z" is bivariate matrix of observations
  inside <- z[, 1]^(-1 / alpha) + z[, 2]^(-1 / alpha)
  log_one <- -inside^alpha
  log_two <- (-1 / alpha - 1) * (log(z[, 1]) + log(z[,
2]))

  three <- (1 / alpha - 1) * inside^(alpha - 2)
  four <- inside^(2 * alpha - 2)
  contrib <- log_one + log_two + log(three + four)
  return(sum(contrib))
}
```

```

    all_pairs_lhood <- function(alpha, z) {
expand.grid(dim1 = seq_len(ncol(z)),                      dim2 =
seq_len(ncol(z))) |> filter(dim1 < dim2) |>
rowwise() |> mutate(log_pair_lhood =
log_pair_lhood(alpha, cbind(z[, dim1], z[, dim2]))) |>
ungroup() |> summarise(res = sum(log_pair_lhood))
|> pull(res) } alpha_mple <-
optim(.2, lower = .01, upper = .99, all_pairs_lhood, z = z, method =
"Brent", hessian = TRUE, control = list(fnscale = -1))
(ci_mple <- alpha_mple$par + c(-1.96, 1.96)*sqrt(-1 /
alpha_mple$hessian[1, 1]))

```

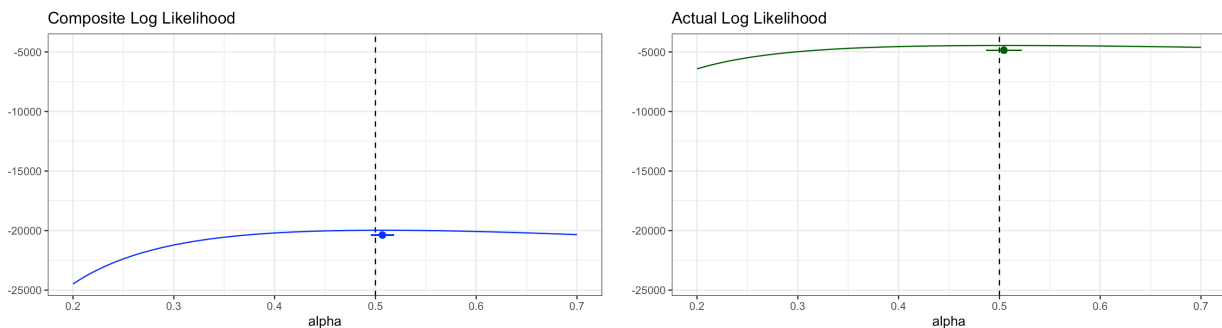
```
## [1] 0.4954979 0.5182678
```

```

## checking coverage
#checking coverage
B <- 200
coverage <- numeric(B)
for(k in seq_len(B)) {
  z_k <- rmvevd(500, dep = .5, d = 5, mar = c(1, 1, 1))
  alpha_mple_k <- optim(.2, lower = .01, upper = .99,
all_pairs_lhood, z = z_k, method = "Brent", hessian = TRUE, control =
list(fnscale = -1))
  ci <- alpha_mple_k$par + c(-1.96, 1.96)*sqrt(-1 /
alpha_mple_k$hessian[1, 1])
  coverage[k] <- as.numeric(ci[1] < alpha & ci[2] > alpha)
}
mean(coverage)

```

```
## [1] 0.745
```



So, it looks like the point estimate from the pairwise likelihood is ok, but we need to be able to get an appropriate measure of uncertainty.

The proper adjustment is

1 Introduction

M-estimators are solutions of the vector equation

$$\sum_{i=1}^n \boldsymbol{\psi}(\mathbf{Y}_i, \boldsymbol{\theta}) = \mathbf{0}.$$

In the likelihood setting, what is $\boldsymbol{\psi}$?

Example: Let Y_1, \dots, Y_n be independent, univariate random variables. Is $\theta = \bar{Y} = \frac{1}{n} \sum_{i=1}^n Y_i$ an M-estimator?

Example: Consider the mean deviation from the sample mean,

$$\hat{\theta}_1 = \frac{1}{n} \sum_{i=1}^n |Y_i - \bar{Y}|.$$

Is this an M-estimator?

2 Basic Approach

M-estimators are solutions of the vector equation

$$\sum_{i=1}^n \psi(\mathbf{Y}_i, \boldsymbol{\theta}) = \mathbf{0}.$$

but what are they estimating?

Example (Sample Mean, cont'd): Recall we said $\theta = \bar{Y} = \frac{1}{n} \sum_{i=1}^n Y_i$ is an M-estimator for $\psi(Y_i, \theta) = Y_i - \theta$. What is the true parameter?

To arrive at the sandwich estimator, assume $\mathbf{Y}_1, \dots, \mathbf{Y}_n \stackrel{iid}{\sim} F$ and define

$$\mathbf{G}_n(\boldsymbol{\theta}) = \frac{1}{n} \sum_{i=1}^n \boldsymbol{\psi}(\mathbf{Y}_i; \boldsymbol{\theta}).$$

Taylor expansion of $\mathbf{G}_n(\boldsymbol{\theta})$ around $\boldsymbol{\theta}_0$ evaluated at $\hat{\boldsymbol{\theta}}$ yields

Define $\mathbf{A}(\boldsymbol{\theta}_0) = \mathbb{E}_F[-\boldsymbol{\psi}'(\mathbf{Y}_1, \boldsymbol{\theta}_0)]$.

2.1 Estimators for A, B

If the data truly come from the assumed parametric family $f(y; \theta)$,

One of the key contributions of M-estimation theory is to point out what happens when the assumed parametric family is not correct.

We can use empirical estimators of A and B :

Example (Coefficient of Variation): Let Y_1, \dots, Y_n be iid from some distribution with finite fourth moment. The coefficient of variation is defined at $\hat{\theta}_3 = s_n/\bar{Y}$.

Define a three dimensional $\boldsymbol{\psi}$ so that $\hat{\theta}_3$ is defined by summing the third component. What is the vector valued function $\boldsymbol{\psi}$ which yields an M-estimator for the coefficient of variation?

What parameter vector is being estimated by the M-estimator?

What are the matrices \mathbf{A} and \mathbf{B} ?

Write out the asymptotic variance, \mathbf{V} .

Assume Y_i are iid from a normal distribution with mean 10 and standard deviation 1. Calculate $V_{3,3}$. Assume you have a sample of size 25 and you get an estimated coefficient of variation of 0.11. Give the asymptotic 95% confidence interval.